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Frank L. Lewis (Eds.)

ADAPTIVE CONTROL
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DYNAMIC SYSTEMS

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Adaptive Control Of Nonsmooth Dynamic Systems

Jing Zhou,Lantao Xing,Changyun Wen

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Adaptive Control of Nonsmooth Dynamic Systems Gang Tao,Frank L. Lewis,2014-03-12 Many of the non smooth non linear phenomena covered in this well balanced book are of vital importance in almost any field of engineering Contributors from all over the world ensure that no one area s slant on the subjects predominates **Adaptive Control of Nonsmooth Dynamic Systems** Gang Tao,Frank L. Lewis,2001-09-26 Many of the non smooth non linear phenomena covered in this well balanced book are of vital importance in almost any field of engineering Contributors from all over the world ensure that no one area s slant on the subjects predominates Adaptive Identification and Control of Uncertain Systems with Non-smooth Dynamics Jing Na,Qiang Chen,Xuemei Ren,2018-06-12 Adaptive Identification and Control of Uncertain Systems with Nonsmooth Dynamics reports some of the latest research on modeling identification and adaptive control for systems with nonsmooth dynamics e g backlash dead zone friction saturation etc The authors present recent research results for the modelling and control designs of uncertain systems with nonsmooth dynamics such as friction dead zone saturation and hysteresis etc with particular applications in servo systems The book is organized into 19 chapters distributed in five parts concerning the four types of nonsmooth characteristics namely friction dead zone saturation and hysteresis respectively Practical experiments are also included to validate and exemplify the proposed approaches This valuable resource can help both researchers and practitioners to learn and understand nonlinear adaptive control designs Academics engineers and graduate students in the fields of electrical engineering control systems mechanical engineering applied mathematics and computer science can benefit from the book It can be also used as a reference book on adaptive control for servo systems for students with some background in control engineering Explains the latest research outputs on modeling identification and adaptive control for systems with nonsmooth dynamics Provides practical application and experimental results for robotic systems and servo motors *Sequential Intelligent Dynamic System Modeling and Control* Hai-Jun Rong,Zhao-Xu Yang,2024-07-05 The book offers novel research results of sequential intelligent dynamic system modeling and control in a unified framework from theory proposals to real applications It covers an in depth study of various learning algorithms for the permanent adaptation of intelligent model parameters as well as of structural parts of the model The comprehensive researches on sequential fuzzy and neural controller design schemes for some complex real applications are included This is particularly suited for readers who are interested to learn practical solutions for controlling nonlinear systems that are uncertain and varied at any time In addition the organization of the book from addressing fundamental concepts and presenting novel intelligent models to solving real applications is one of the major features of the book which makes it a valuable resource for both beginners and researchers wanting to further their understanding and study about realtime online intelligent modeling and control ofnonlinear dynamic systems The book can benefit researchers engineers and graduate students in the fields of control engineering artificial intelligence computational intelligence intelligent control nonlinear

system modeling and control etc   **Adaptive Backstepping Control of Uncertain Systems** Jing Zhou,Changyun Wen,2008-01-08 This book employs the powerful and popular adaptive backstepping control technology to design controllers for dynamic uncertain systems with non smooth nonlinearities Various cases including systems with time varying parameters multi inputs and multi outputs backlash dead zone hysteresis and saturation are considered in design and analysis For multi inputs and multi outputs systems both centralized and decentralized controls are addressed This book not only presents recent research results including theoretical success and practical development such as the proof of system stability and

Fundamental Research in Electrical Engineering Shahram Montaser Kouhsari,2018-07-25 This volume presents the selected papers of the First International Conference on Fundamental Research in Electrical Engineering held at Khwarazmi University Tehran Iran in July 2017 The selected papers cover the whole spectrum of the main four fields of Electrical Engineering Electronic Telecommunications Control and Power Engineering   Replication of Chaos in Neural Networks, Economics and Physics Marat Akhmet,Mehmet Onur Fen,2015-08-13 This book presents detailed descriptions of chaos for continuous time systems It is the first ever book to consider chaos as an input for differential and hybrid equations Chaotic sets and chaotic functions are used as inputs for systems with attractors equilibrium points cycles and tori The findings strongly suggest that chaos theory can proceed from the theory of differential equations to a higher level than previously thought The approach selected is conducive to the in depth analysis of different types of chaos The appearance of deterministic chaos in neural networks economics and mechanical systems is discussed theoretically and supported by simulations As such the book offers a valuable resource for mathematicians physicists engineers and economists studying nonlinear chaotic dynamics   **Trends in Intelligent Robotics** Prahlad Vadakkepat,Jong-Hwan Kim,Norbert Jesse,Abdullah Al Mamun,Tan Kok Kiong,Jacky Baltes,John Anderson,Igor Verner,David Ahlgren,2010-09-01 th This volume contains the papers selected for the 13 FIRA Robot World Congress held at Amrita Vishwa Vidyapeetham Bangalore India September 15 17 2010 The Federation of International Robot soccer Association FIRA www fira net is a non profit organization that annually organizes robotic competitions and meetings around the globe The robot soccer competitions started in 1996 and FIRA was est lished on June 5 1997 The robot soccer competitions are aimed at promoting the spirit of science and technology to the younger generation The congress is a forum to share ideas and future directions of technologies and to enlarge the human networks in the robotics area The objectives of the FIRA Cup and Congress are to explore the technical dev opments and achievements in the field of robotics and provide participants with a robot festival including technical presentations robot soccer competitions and exh its under the theme Where Theory and Practice Meet FIRA India aims to propagate and popularize robotics and robotic competitions across India   *Advanced Discrete-Time Control* Khalid Abidi,Jian-Xin Xu,2015-03-25 This book covers a wide spectrum of systems such as linear and nonlinear multivariable systems as well as control problems such as disturbance uncertainty and time delays The purpose of this book is to provide

researchers and practitioners a manual for the design and application of advanced discrete time controllers The book presents six different control approaches depending on the type of system and control problem The first and second approaches are based on Sliding Mode control SMC theory and are intended for linear systems with exogenous disturbances The third and fourth approaches are based on adaptive control theory and are aimed at linear nonlinear systems with periodically varying parametric uncertainty or systems with input delay The fifth approach is based on Iterative learning control ILC theory and is aimed at uncertain linear nonlinear systems with repeatable tasks and the final approach is based on fuzzy logic control FLC and is intended for highly uncertain systems with heuristic control knowledge Detailed numerical examples are provided in each chapter to illustrate the design procedure for each control method A number of practical control applications are also presented to show the problem solving process and effectiveness with the advanced discrete time control approaches introduced in this book   Journal of Dynamic Systems, Measurement, and Control ,2007

Neural Computing for Advanced Applications Haijun Zhang,Yuehui Chen,Xianghua Chu,Zhao Zhang,Tianyong Hao,Zhou Wu,Yimin Yang,2022-10-20 The two volume Proceedings set CCIS 1637 and 1638 constitutes the refereed proceedings of the Third International Conference on Neural Computing for Advanced Applications NCAA 2022 held in Jinan China during July 8 10 2022 The 77 papers included in these proceedings were carefully reviewed and selected from 205 submissions These papers were categorized into 10 technical tracks i e neural network theory and cognitive sciences machine learning data mining data security privacy protection and data driven applications computational intelligence nature inspired optimizers and their engineering applications cloud edge fog computing the Internet of Things Vehicles IoT IoV and their system optimization control systems network synchronization system integration and industrial artificial intelligence fuzzy logic neuro fuzzy systems decision making and their applications in management sciences computer vision image processing and their industrial applications natural language processing machine translation knowledge graphs and their applications Neural computing based fault diagnosis fault forecasting prognostic management and system modeling and Spreading dynamics forecasting and other intelligent techniques against coronavirus disease COVID 19   **Applied Mechanics Reviews** ,1995   **Nonlinear Robust and Adaptive Control with Application to Brake Control for Automated Highway Systems** Dragos Bogdan Maciuca,1997   **Proceedings of the ASME Dynamic Systems and Control Division** ,2006   Adaptive Control of Nonlinear Dynamic Systems Daniel Yves Abramovitch,1988   **Digests of APMRC.** ,2002   **Proceedings of the ... American Control Conference** ,2005   Adaptive Backstepping Control of Uncertain Systems with Actuator Failures, Subsystem Interactions, and Nonsmooth Nonlinearities Wei Wang,Changyun Wen,Jing Zhou,2017-09-18 In practice actuators often undergo failures and various factors influence its effectiveness Also due to the increasing complexity of large scale systems subsystems are often interconnected whereas the interactions between any two subsystems are difficult to deal with This book details a series of new methodologies of designing and

analyzing adaptive backstepping control systems involving treatment on actuator failures subsystem interactions and nonsmooth nonlinearities Moreover it discusses some interesting open issues in adaptive failure accommodation decentralized adaptive control and distributed adaptive coordinated control **Adaptive Control of Dynamic Systems with Uncertainty and Quantization** Jing Zhou,Lantao Xing,Changyun Wen,2021-12-14 This book presents a series of innovative technologies and research results on adaptive control of dynamic systems with quantization uncertainty and nonlinearity including the theoretical success and practical development such as the approaches for stability analysis the compensation of quantization the treatment of subsystem interactions and the improvement of system tracking and transient performance Novel solutions by adopting backstepping design tools to a number of hotspots and challenging problems in the area of adaptive control are provided In the first three chapters the general design procedures and stability analysis of backstepping controllers and the basic descriptions and properties of quantizers are introduced as preliminary knowledge for this book In the remainder of this book adaptive control schemes are introduced to compensate for the effects of input quantization state quantization both input and state output quantization for uncertain nonlinear systems and are applied to helicopter systems and DC Microgrid Discussion remarks are provided in each chapter highlighting new approaches and contributions to emphasize the novelty of the presented design and analysis methods Simulation results are also given in each chapter to show the effectiveness of these methods This book is helpful to learn and understand the fundamental backstepping schemes for state feedback control and output feedback control It can be used as a reference book or a textbook on adaptive quantized control for students with some background in feedback control systems Researchers graduate students and engineers in the fields of control information and communication electrical engineering mechanical engineering computer science and others will benefit from this book *Adaptive Control of Systems with Nonsmooth Nonlinearities* Ming Tian,1997

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