



Stephen Lynch

Dynamical Systems with Applications Using MATLAB[®]

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Differential Dynamical Systems James D. Meiss,2007-01-01 Differential equations are the basis for models of any physical systems that exhibit smooth change This book combines much of the material found in a traditional course on ordinary differential equations with an introduction to the more modern theory of dynamical systems Applications of this theory to physics biology chemistry and engineering are shown through examples in such areas as population modeling fluid dynamics electronics and mechanics Differential Dynamical Systems begins with coverage of linear systems including matrix algebra the focus then shifts to foundational material on nonlinear differential equations making heavy use of the contraction mapping theorem Subsequent chapters deal specifically with dynamical systems conceptsflow stability invariant manifolds the phase plane bifurcation chaos and Hamiltonian dynamics Throughout the book the author includes exercises to help students develop an analytical and geometrical understanding of dynamics Many of the exercises and examples are based on applications and some involve computation an appendix offers simple codes written in Maple Mathematica and MATLAB software to give students practice with computation applied to dynamical systems problems Audience This textbook is intended for senior undergraduates and first year graduate students in pure and applied mathematics engineering and the physical sciences Readers should be comfortable with elementary differential equations and linear algebra and should have had exposure to advanced calculus Contents List of Figures Preface Acknowledgments Chapter 1 Introduction Chapter 2 Linear Systems Chapter 3 Existence and Uniqueness Chapter 4 Dynamical Systems Chapter 5 Invariant Manifolds Chapter 6 The Phase Plane Chapter 7 Chaotic Dynamics Chapter 8 Bifurcation Theory Chapter 9 Hamiltonian Dynamics Appendix Mathematical Software Bibliography Index

Dynamical Systems with Applications using MAPLE Stephen Lynch,2001 The text treats a remarkable spectrum of topics and has a little for everyone It can serve as an introduction to many of the topics of dynamical systems and will help even the most jaded reader such as this reviewer enjoy some of the interactive aspects of studying dynamics using Maple UK Nonlinear News Review of First Edition The book will be useful for all kinds of dynamical systems courses It shows the power of using a computer algebra program to study dynamical systems and by

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introduction to the theory of dynamical systems with the aid of the Maple algebraic manipulation package It is written for both senior undergraduates and graduate students The first part of the book deals with continuous systems using ordinary differential equations Chapters 1-10 the second part is devoted to the study of discrete dynamical systems Chapters 11-15 and Chapters 16-18 deal with both continuous and discrete systems Chapter 19 lists examination type questions used by the author over many years one set to be used in a computer laboratory with access to Maple and the other set to be used without access to Maple Chapter 20 lists answers to all of the exercises given in the book It should be pointed out that dynamical systems theory is not limited to these topics but also encompasses partial differential equations integral and integro-differential equations stochastic systems and time delay systems for instance References 1-5 given at the end of the Preface provide more information for the interested reader

Dynamical Systems with Applications using Mathematica® Stephen Lynch, 2008-11-01 This book provides an introduction to the theory of dynamical systems with the aid of the Mathematica computer algebra package The book has a very hands on approach and takes the reader from basic theory to recently published research material Emphasized throughout are numerous applications to biology chemical kinetics economics electronics epidemiology nonlinear optics mechanics population dynamics and neural networks Theorems and proofs are kept to a minimum The first section deals with continuous systems using ordinary differential equations while the second part is devoted to the study of discrete dynamical systems

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